

**GRUPPO ESEA** 

Via Nazionale, 56/A - 65012 Cepagatti (PE) - ITALY Tel: +39 0871562636 Email: info@gruppoesea.it

Homepage: www.gruppoesea.it - in

## **DATA SHEET**

## Model: EFESTO

Automatic Fiber Placement (AFP)

## **Product INFO**

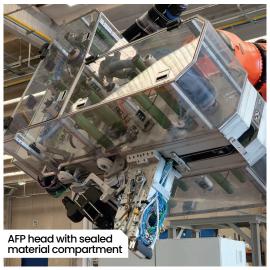
ESEA modular AFP head has demonstrated high productivity and high quality in the aerospace production.

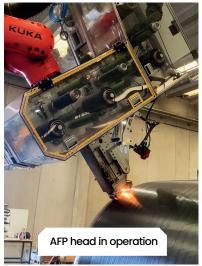
This innovative AFP head has been developed to optimize the capability to work on complex convex and concave structures. The user friendly programming software supports tailored trajectories to ease the production.

The EFESTO head improves the technology by using:

- different sizes of slittape or towpreg in one head
- rapid set-up
- high laying accuracy
- high productivity in production









## TECHNICAL DATA

<b>AFP PROCESS S</b>	PECIFICATIONS
----------------------	---------------

	AFF PROCESS SPECIFICATIONS		
	Head configuration	Modular approach. The head can be assembled in different configuration. The basic configuration is equipped with 4 spools (basic design). It is possibile to add a second set of 4 spools to increase the productivity. It is possible in alternative to remove the spool delivery device by each side of the head.	
	High accuracy robot laying	+/- 0,1 mm	
	Fiber configuration	1/4'' and 1/2''	
	Cut and feed repeatability	± 2 mm at 700 mm/s	
	Compaction force control	3 N to 30 N (automatic, sectable along trajectory)	
	Temperature and Humidity head control	6° to 20°	
	Maximum lay-up speed	Up to 1,2 m/s	
	Tolerance between laid tapes	0/+0,2 mm	
	Minimum fiber length	100 mm	
	Tape tension	3 N to 20 N	
	Spool (on board)	4+4	
	Release film rewinder	4+4	
	HMI for advanced production management	Visual process control with intuitive windows	
	• •	for operation and maintenance	
	Bar-code reader for material traceability		
	Offline simulation software	VERICUT VCS Composites solution 9.4.2	•
	Offline postprocessing software	VERICUT VCP Composites programming 9.4.2	•
	IP CAMERA	Visual control cam during operation	•
	Quality assurance	Laser profilometer, recording and storage	. 1
		of the main process parameters	•
	CELL CONFIGURATIONS		
	Robot Kuka	KR600	•
	Robot on a linear axis	Up to 80 m in length	
	Tool AFP		
0	Humidity and temperature head air control		
	IR Heater	500 W	
0	IR Camera control		
	Electrical Cabinet	Insulation code IP56 and air condition system	
	Horizontal positioner		
•	Payload	40,000 kg	
	Maximum mandrel diameter	Ø 2,500 mm	
0	Maximum mandrel lenght	10,000 mm	
	Angular accuracy	0,005°	
	COMPONENTS		
•	Robot	Kuka	
	Controller	Siemens CNC	
	Linear axis	Güdel	
	Positioner	ESEA Composites	
	MATERIALS		
	Termoset Tape	Compatible	
	Thermoplastic Towpreg	Compatible	
	OPTIONS		
	Laser heater	For thermoplastic process with optical zoom to adapt the laser spot to the bandwidth and trajectory specifics.	
	Vertical axis positioner		
	• Payload	5,000 kg	
	• Table Diameter	2,700 mm	
	Angular accuracy	0,005°	
	Smart maintenance service with augmented reality functions		